Optimization of Metal Refinement Process by Selecting the Optimal Threshold Value

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Abstract: The purpose of study is to find the optimal threshold value for metal refinement processes based on Taguchi loss function. Taguchi method is a widely employed methodology in many different industries for improving the performance of product/process. In Taguchi’s dynamic systems, if both input and output have only two digital values (0 and 1) with the possibility of committing two types of errors (judging 0 as 1 and 1 as 0), such a problem is called the digital system. Metal refinement processes can be viewed as a digital dynamic problem when the goal is to separate the metal molecules from the impurities. Molten metal stays at the bottom and the impurities float as slag on the top of molten metal. For this purpose, a threshold value \( R \) is required to discriminate molten metal from slag. A material is assessed as valuable metal or slag depending on the corresponding output, which is affected by control factors and noise factors. If output is less than this threshold value \( R \) then it may be considered slag and if value comes greater than or equal to threshold value \( R \) then considered valuable metal. Two types of error rate are occurred, \( p \) percent of metal molecules go into slag and \( q \) percent of a particular impurity go into the molten metal. This paper views the error rates as random variables with normal distributions and find the setting value of threshold \( R \) for the cases of loss coefficients are unequal.

Keywords: Digital dynamic system, error rate, threshold value, loss function.

1. Introduction

Gaining global competitiveness in terms of innovative product development, satisfying demanding mass customization requirements from customers, high quality assurance, fast time-to-market and cost reductions are becoming critical success factors for many companies. Taguchi [1] method is a widely employed methodology in many different industries for improving the performance of product/process of both static and dynamic systems. A static system is defined as one where the desired output of a system has a fixed target. Problems where the output varies depending on the input are classified as a dynamic system. If both input and output have only two digital values (0 and 1) with the possibility of committing two types of errors, such a problem is called digital dynamic system.

Taguchi used the signal-to-noise (SN) ratio to determine the optimal parameter settings, which is a statistic derived from the quality loss function. A higher SN ratio means a lower loss. In case of the digital dynamic, Taguchi recommended calculating the equalized error rates first by a leveling operation based on the two errors \( p \) and \( q \) with the same loss coefficient to optimize the parameter settings for such a problem.
The equalized error rate is denoted by $p_0$ ($p_0 = p' = q'$) as

$$p_0 = \left[ 1 + \sqrt{(1/p-1)(1/q-1)} \right]^{-1} \quad (1)$$

Several researchers have studied robust design problem concerning the dynamic systems. Chen [2] developed the SN ratio for four cases of dynamic characteristic problems. They also presented the method to compute SN ratios both equispaced and non-equispaced intervals for levels of signal factors. Miller and Wu [3] pointed out the deficiencies to Taguchi’s dynamic SN ratio approach and then provided two strategies for modeling and analyzing data of dynamic systems. Wasserman [4] illustrated the parameter design of dynamic system with the regression perspective. Lunani, Nair and Wasserman [5] demonstrated the limitations of data analysis methods recommended by Taguchi and then proposed two graphical methods for identifying suitable measures of dispersion and for data analysis. McCaskey and Tsui [6] developed an appropriate two-step procedure for dynamic systems under an additive model. This procedure reduces the dimension of the optimization problem and allows for future changes of the target slope without re-optimization. Su and Hsieh [7] presented an approach based on neural network technique to achieve optimization of dynamic systems. Tsui [8] investigated the response model analysis under an additive model and a linear response-to-signal relationship. Kapur and Li [9] presented three models for the establishment of the optimal parameter conditions by selection of the optimal threshold value for digital system. Chen [10] provided a stochastic optimization modeling procedure to accommodate dynamic characteristics. The advantage of this method is that it does not require any performance measure as the SN ratio. Wu and Yeh [11] presented an approach to optimizing multiple dynamic problems based on quality loss. Wu [12] developed the signal factor contribution as SN ratio to optimize the digital system. Lai, Wu and Chen [13] investigated the correlated loss coefficient between two quality characteristics to optimize the parameter conditions by selection of optimal threshold value for the digital system. Wu [14] used the double-exponential desirability function to optimize the parameter design for the nonlinear multiple dynamic systems. Wu, Wang and Fan [15] proposed a general model for optimizing parameter design and selecting threshold value for the digital systems where the output is classified into four classes.

This paper applies the concept of Taguchi quality loss function to view the error rates as random variables and optimize the digital system and find the setting value of threshold $R$ for the cases of loss coefficients are unequal.

## 2. Digital Dynamic System

In digital systems for metal refinement process, both signal (input) and response (output) are classified into two classes: S and M. The ideal function is that whenever an input signal is S, the output should be S, and whenever the input signal is M, the output should be M. Thus, the signal values for testing are $x_0=S$ and $x_1=M$. Suppose the output is a continuous random variable affected by control factors $Z$ and noise factors $N$, the criterion for judging the output is the threshold value $R$. If output $y_0$ is smaller than threshold $R$, $y_0$ is set as S when input signal $x_0$ is S. Similarly, if output $y_1$ is larger than threshold $R$, $y_1$ is set as M when input signal $x_1$ is M. Fig. 1 describes the model of digital system.

Suppose that under certain settings of control factors and noise conditions, the error rate $p$ is the probability of wrongly classifying signal S as M, and $q$ is the probability of wrongly classifying signal M as S. The input/output table in terms of error rates $p$ and $q$ is tabulated in Table 1. The input/output relationship of error rates $p$, $q$ and threshold value $R$ is shown graphically in Fig. 2.
3. Quality Loss Model of Metal Refinement Process

Let the random variables $X$ and $Y$ represent the results of a metal refinement process on the slag and valuable metal populations having independent normal distributions $X \sim N(\mu_X, \sigma_X^2)$, and $Y \sim N(\mu_M, \sigma_M^2)$ respectively, and assume that $\mu_M > \mu_S$. The error rate $p$ for impurities go into the metal and error rate $q$ for metal molecules go into the slag are presented as

$$p = 1 - \Phi\left(\frac{R - \mu_S}{\sigma_S}\right)$$  \hspace{1cm} (2)

$$q = \Phi\left(\frac{R - \mu_M}{\sigma_M}\right)$$  \hspace{1cm} (3)

where $\Phi(\cdot)$ is the standard normal cumulative distribution function.

When the error rate is $p$ for impurities go into the metal, on average, we will manufacture $\frac{1}{1-p}$ products to produce one good product. Thus, a loss is equivalent to the cost of processing $\frac{1}{(1-p)} - 1 = p/(1-p)$ products. Let $K_1$ be the cost of processing one product, the quality loss $L_1$ is
\[ L_1 = K_1 \cdot (1 - p)/p = K_1 \cdot [1/p - 1] = K_1 \cdot \left[ (1 - \Phi \left( \frac{(R - \mu_s)}{\sigma_s} \right))^{-1} - 1 \right] \] (4)

Similarly, let \( K_2 \) be the cost of processing one product when the error rate is \( q \) for metal molecules going into the slag. The quality loss \( L_2 \) is given by

\[ L_2 = K_2 \cdot (1 - q)/q = K_2 \cdot [1/q - 1] = K_2 \cdot \left[ \Phi \left( \frac{(R - \mu_u)}{\sigma_u} \right))^{-1} - 1 \right] \] (5)

The total quality loss of processing 100% \( S_{SR}(R) \) and 100% \( S_{ER}(R) \) is represented by

\[ L(R) = K_1 \cdot \left[ (1 - \Phi \left( \frac{(R - \mu_s)}{\sigma_s} \right))^{-1} - 1 \right] + K_2 \cdot \left[ \Phi \left( \frac{(R - \mu_u)}{\sigma_u} \right))^{-1} - 1 \right] \] (6)

The value of \( R_T \) that achieves this minimum quality loss will be considered the optimal threshold value \( R_T^* \).

\[ R_T^* = \min_x[L(R)] = \min_x \left[ K_1 \cdot \left[ (1 - \Phi \left( \frac{(R - \mu_s)}{\sigma_s} \right))^{-1} - 1 \right] + K_2 \cdot \left[ \Phi \left( \frac{(R - \mu_u)}{\sigma_u} \right))^{-1} - 1 \right] \] (7)

Differentiating \( L(R) \) with respect to \( c \) and then setting the derivative equal to zero, we can obtain \( R_T^* \). Unfortunately, there is no closed-form solution available for the cumulative normal distribution. Hence, we adopt the logistic approximation function to the cumulative normal distribution proposed by Bowling et al. (16), which is expressed as

\[ \Phi(z) \approx (1 + \exp(-1.702 \cdot z))^{-1} \] (8)

Therefore, optimal threshold value \( R_T^* \) is given by

\[ R_T^* = 1.702 \left( \mu_s \sigma_u + \mu_u \sigma_s \right) + \sigma_s \sigma_u \ln \left( K_1 \cdot \sigma_s / K_2 \cdot \sigma_u \right) / \left( 1.702 (\sigma_s + \sigma_u) \right) \] (9)

We can redefine the SN ratio before a leveling operation for the digital dynamic system as

\[ \eta_{df} = -10 \log \left( L(R_T^*) \right) = -10 \log \left[ K_1 \cdot \left[ (1 - \Phi \left( R_T^* - \mu_s \right))^{-1} - 1 \right] + K_2 \cdot \left[ \Phi \left( R_T^* - \mu_u \right))^{-1} - 1 \right] \right] \] (10)

4. Conclusion

The digital system is widely applied in areas. Examples are the evaluation of good and inferior products in a defective checking system and the separation process of ore into valuable metal and slag. These can be considered examples of such a system that has two kinds of errors. Taguchi suggested making the two error rates equal by adjusting the threshold value and then calculating the standardized SN ratio to obtain the optimal parameter settings. However, Taguchi’s model based on the loss coefficients being equal is generally not suitable in practice. This paper provides a general model to find the optimal threshold value and a novel SN ratio before a leveling operation to optimize the digital dynamic systems based on Taguchi.
loss function.

References


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